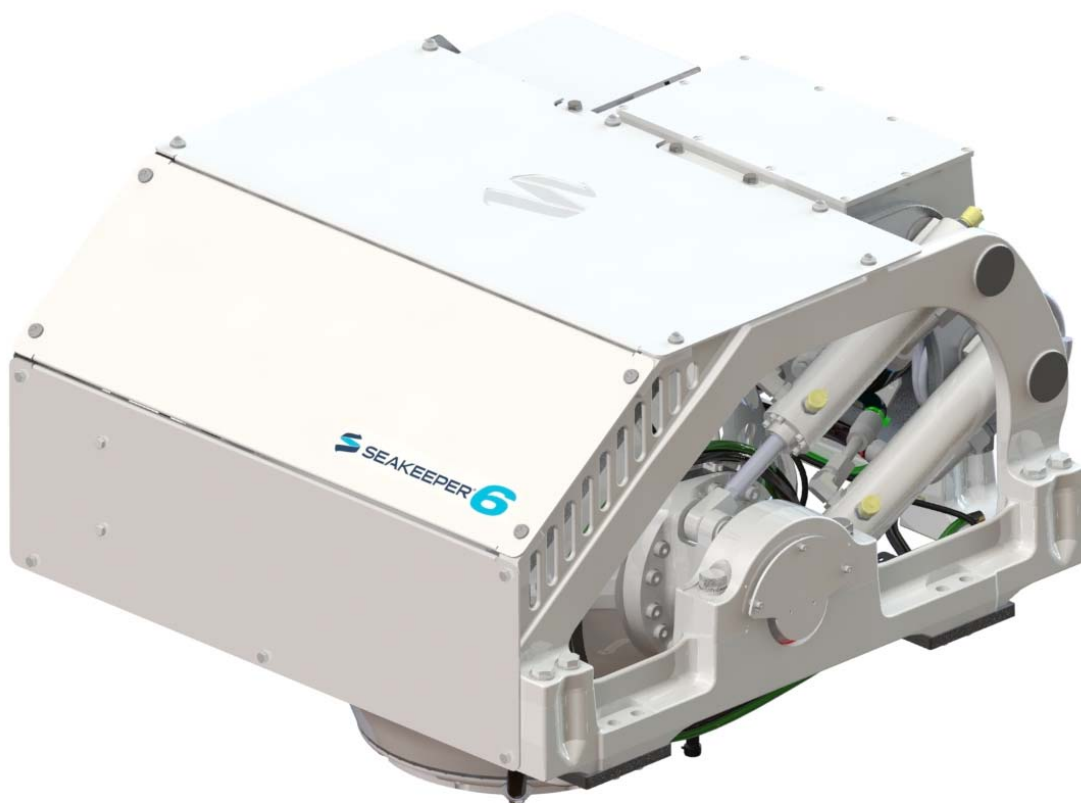





SEAKEEPER

OPERATION MANUAL



 SEAKEEPER	OPERATION MANUAL	Product:	Document #:	Rev:
		SEAKEEPER 6	90403	1

SEAKEEPER 6

OPERATION MANUAL

JUNE 2017

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Section 1: SYSTEM OVERVIEW

1.0 System Overview

The Seakeeper 6 uses gyroscopic principles to reduce boat roll motions in waves and wakes independent of boat speed. In multiple Seakeeper installations, the Seakeepers operate independently of each other and therefore this manual only discusses operation of a single unit.

A Seakeeper 6 consists of a Seakeeper assembly, a CAN communications cable, and a Display. Figure 1 illustrates the interconnection of these components and their interface with the boat.

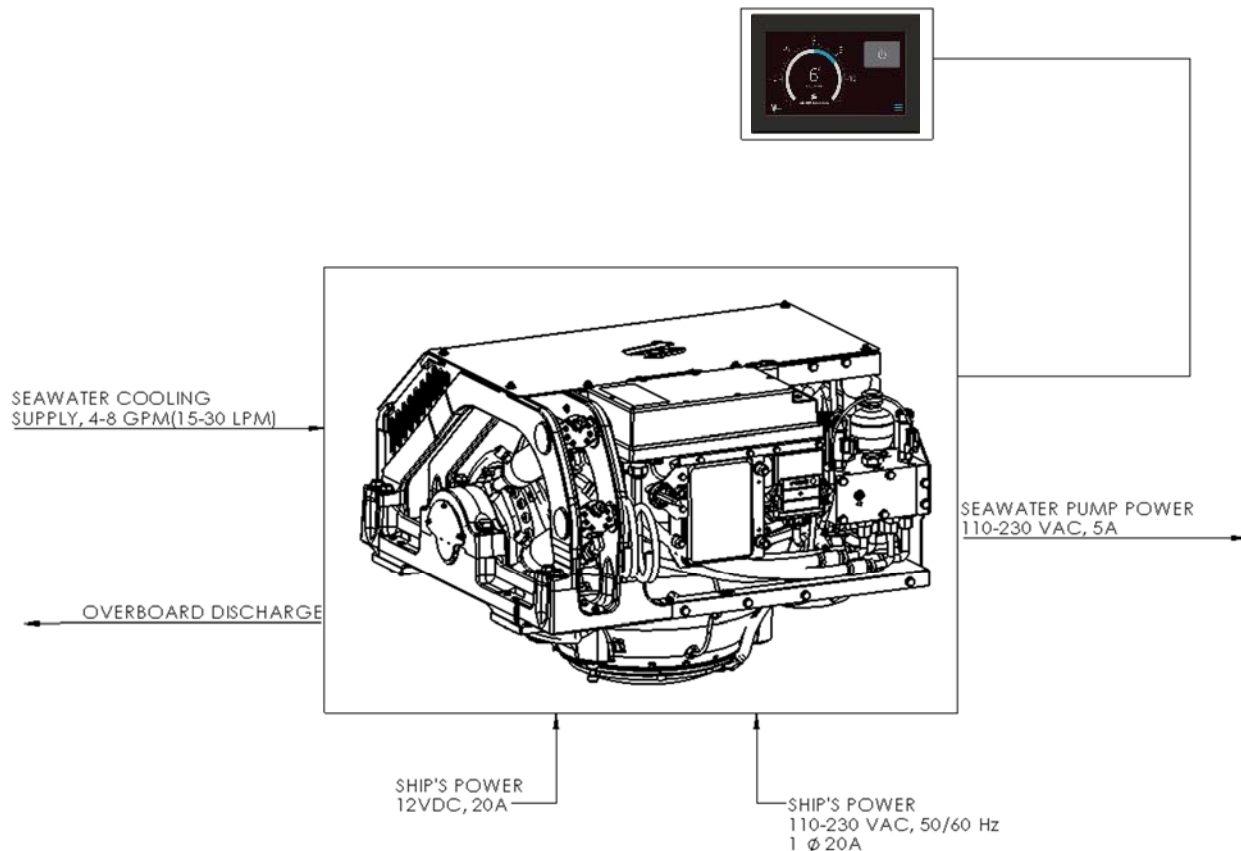


FIGURE 1 – SEAKEEPER 6 STABILIZATION SYSTEM COMPONENTS

Technical specifications provided in Section 6 list the power consumption, total weight, and dimensions of the major components. Gyroscopic principals that apply to boat roll control are discussed on Seakeeper’s web site at www.seakeeper.com. The Seakeeper web site also contains videos of Seakeeper operation and videos of several different boats operating in waves with the Seakeeper on and off. It is recommended that the reader play these videos prior to reading the remainder of this manual.

Section 1: SYSTEM OVERVIEW

The Seakeeper's gimbal angle and the Seakeeper's rate of rotation about the gimbal axis (termed precession rate) play an important role in its operation. These parameters are illustrated in Figure 2. At zero degree gimbal angle, the Seakeeper is vertical; it can precess a maximum of +/- 60 degrees about this position. The amount of torque that the Seakeeper exerts on a boat's hull to counter the wave induced roll is directly proportional to the precession rate. The further the Seakeeper is from vertical (zero degrees) the lower the anti-roll torque. The vertical arrows in Figure 2 illustrate the direction of the forces that the Seakeeper exerts on the boat's hull to damp roll motion.

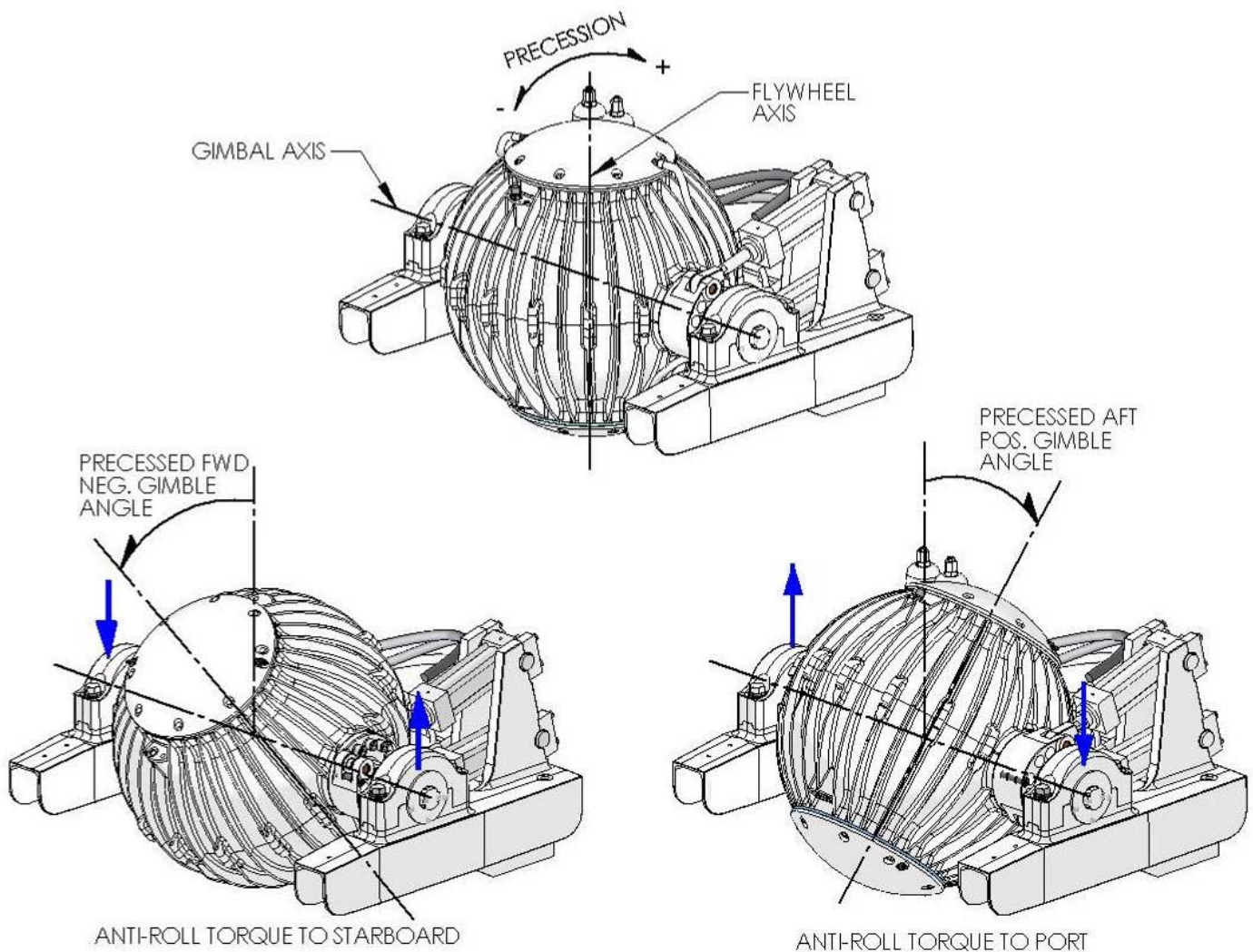


FIGURE 2 – SEAKEEPER PRECESSION

Seakeeper precession is actively controlled by an electronic controller and a hydraulic brake throughout each roll cycle so the Seakeeper supplies the maximum anti-roll torque and does not make mechanical contact with hard stops that limit the maximum gimbal angle travel to +/- 60°.

Section 1: SYSTEM OVERVIEW

There is a large torque about the gimbal axis when the Seakeeper is precessing. Seakeeper cover panels are provided to prevent personnel or equipment from contacting the Seakeeper while it is in operation. These covers should not be stood on, or have anything placed on top. The covers should always be in place during operation. If it is ever necessary to touch the Seakeeper while the flywheel is spinning, the Seakeeper must be locked at the display to stop the Seakeeper from precessing. Seakeeper maintenance should not be attempted unless the Seakeeper is locked and the flywheel has stopped spinning.

Section 1: SYSTEM OVERVIEW

1.1 Seakeeper Assembly

The Seakeeper assembly consists of a flywheel housed in a cast aluminum vacuum-tight enclosure. The flywheel spins about a vertical axis and is supported by upper and lower pairs of bearings. A DC brushless motor mounted inside the enclosure spins the flywheel at high speed.

The enclosure is fastened to two gimbal shafts that are supported by gimbal bearings on either side. These shafts establish an athwartship gimbal axis about which the flywheel and enclosure precess or rotate up to +/- 60 degrees during operation. The gimbal bearings are supported by a foundation which is attached to the hull structure. This foundation transfers the loads that the Seakeeper produces to the hull structure.

An active hydraulic brake mechanism is located on the Seakeeper assembly to regulate the Seakeeper's precession motions about the gimbal shaft. It includes two hydraulic cylinders and a hydraulic manifold.

A coolant pump, heat exchanger with reservoir, and thermostat are located near the manifold. A glycol/water mix is circulated thru a closed loop to the drive box, hydraulic manifold, and the end caps of the enclosure to remove heat.

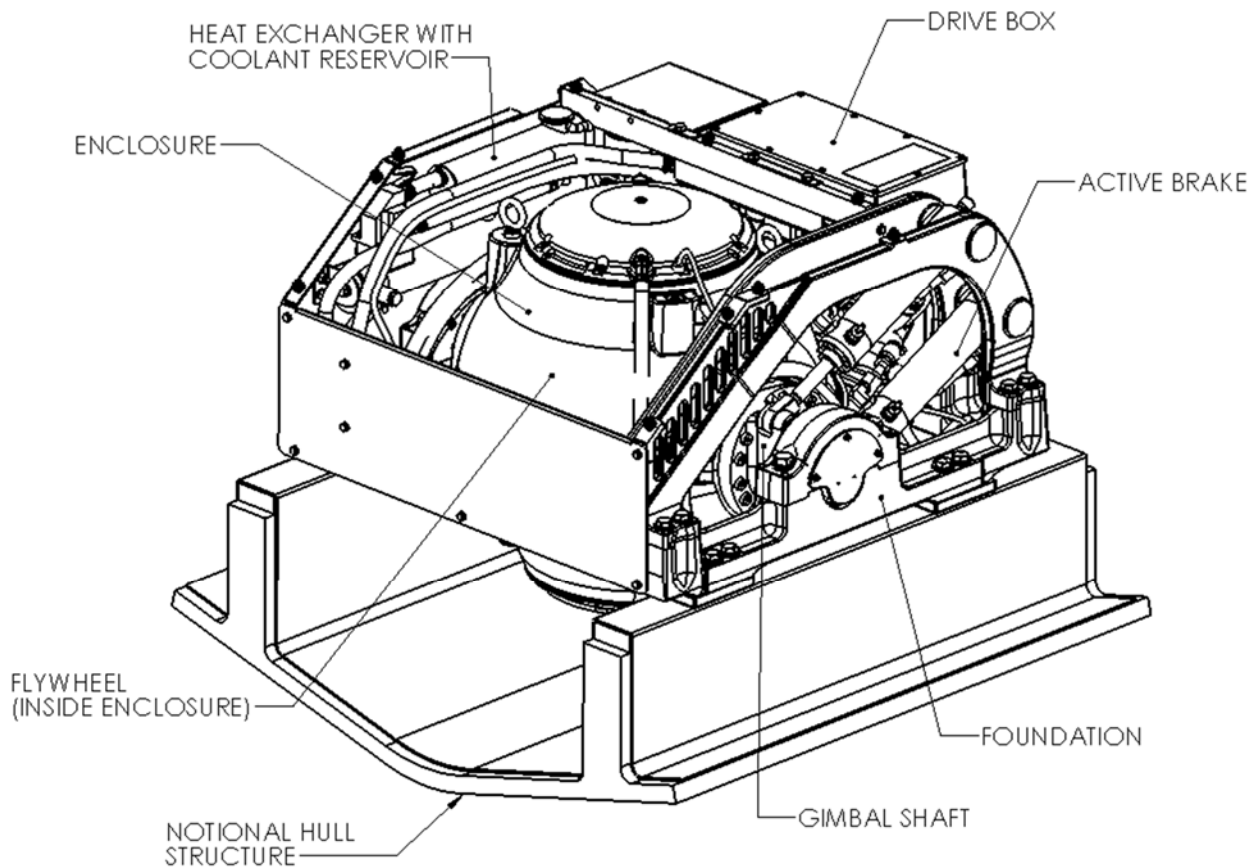


FIGURE 3 – SEAKEEPER ASSEMBLY

Section 1: SYSTEM OVERVIEW

1.2 Display

The display shown below is the user interface to the Seakeeper 6 and should be mounted at the primary helm station. It is used to start, operate, monitor and shutdown the Seakeeper. Sensors, alarms and shutdowns are provided to allow unattended operation.

The display provides information in the event of an alarm. Alarms cause precession to stop (Stabilize Off) and the Seakeeper to start coasting down (Seakeeper Off).



FIGURE 4 – OPERATOR DISPLAY

Section 1: SYSTEM OVERVIEW

1.3 Drive Box

The Drive Box contains the electronic components that take 110-230 VAC at 50/60 Hz from the boat's generator or shore power and supply current to the flywheel motor according to commands from the Electronic Control Module (ECM). The glycol/water mix that cools the Seakeeper is also circulated through a cold plate inside the Drive Box to remove heat from high-power electronic components.



The Drive Box contains high voltage electronics and the cover should not be removed while the flywheel is spinning except by an authorized technician. This high voltage exists even if the flywheel is coasting down and the supply voltage has been shut off.

DRIVE BOX

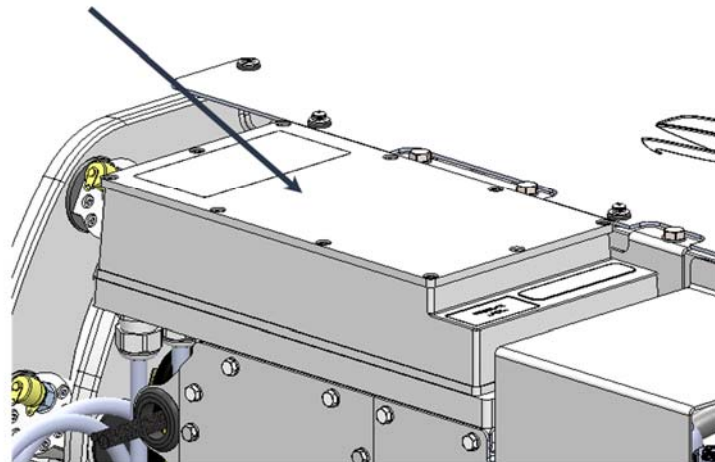


FIGURE 5 – DRIVE BOX

Section 1: SYSTEM OVERVIEW

1.4 Electronic Control Module

The Electronic Control Module (ECM) monitors all the system sensors and automatically regulates operation of the Seakeeper.

The controller commands the motor speed and regulates the Seakeeper's precession rate and gimbil angle. This is accomplished by commands to a high response flow control valve in the hydraulic brake circuit that increases or decreases the brake pressure.

1.5 Inertia Measurement Unit (IMU)

The motion sensor suite in the IMU contains rate sensors that measure the angular movements of the vessel and accelerometers that measure the vertical and lateral boat movement. These signals are communicated to the ECM on a CANbus connection inside the Seakeeper's wiring harness.

1.6 Brake

The brake mechanism consists of two hydraulic cylinders that attach to a crank arm on the Seakeeper gimbal shaft. The Seakeeper controller modulates how fast the oil can flow through a control valve thus controlling the precession rate of the Seakeeper.

The brake hydraulic circuit is a pre-charged closed loop – that is, there is no pump, motor or reservoir in the circuit. Accumulators are installed in the circuit so the precharge pressure does not increase as the fluid temperature rises due to the braking action. Locking solenoids are installed in the circuit to lock the Seakeeper so it cannot precess during 'lock' mode or if there is a leak in the circuit or a mechanical problem with the Seakeeper.

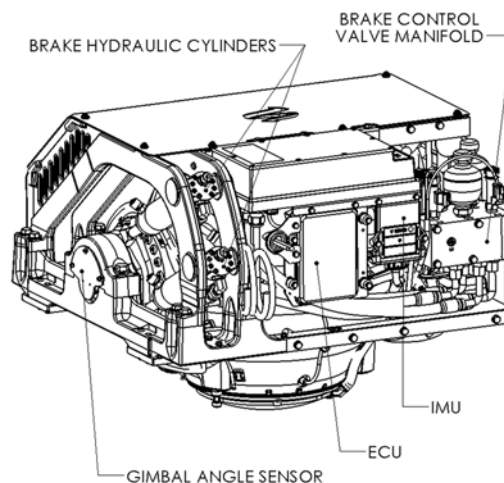


FIGURE 6 – BRAKE SYSTEM COMPONENTS

Seakeeper hydraulic Hand Pump Kit, P/N 10384, is required for servicing the brake system.
Pressure should never be relieved unless this tool is available.

Section 1: SYSTEM OVERVIEW

1.7 Cooling

The cooling circuit is a closed loop that supplies a glycol/water (50% distilled water and 50% glycol) mix to:

- The motor drive box to remove heat from the drive electronics
- The brake manifold to remove heat from the brake hydraulic circuit
- The Seakeeper enclosure water jackets to remove heat from the flywheel bearings

The heated fluid then passes through a thermostat before bypassing or flowing through a heat exchanger that has sea water on the cold side. The circuit also contains a coolant reservoir for coolant expansion and to make filling easy. The reservoir contains a 7 psi (0.5 bar) pressure cap.

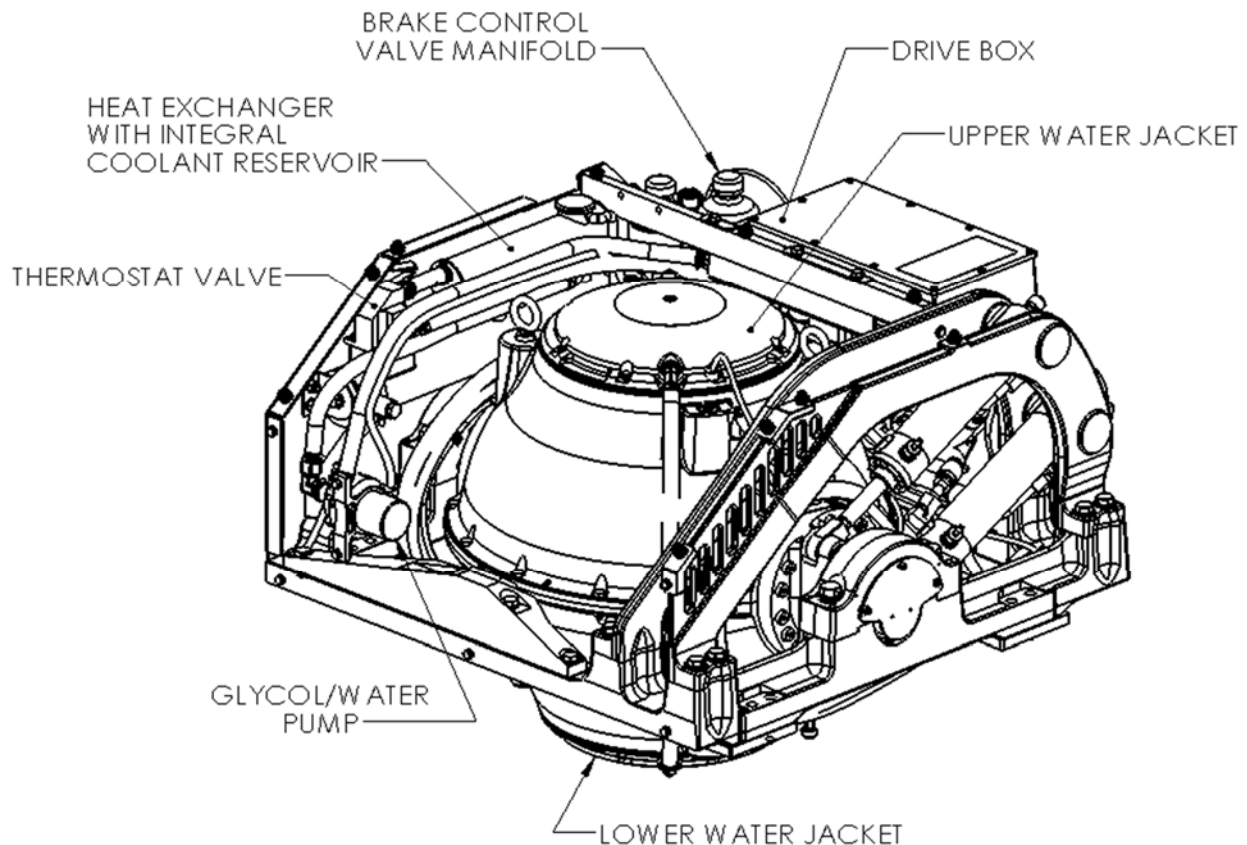


FIGURE 7 – COOLING SYSTEM COMPONENTS

Section 2: SYSTEM OPERATION

2.0 Introduction

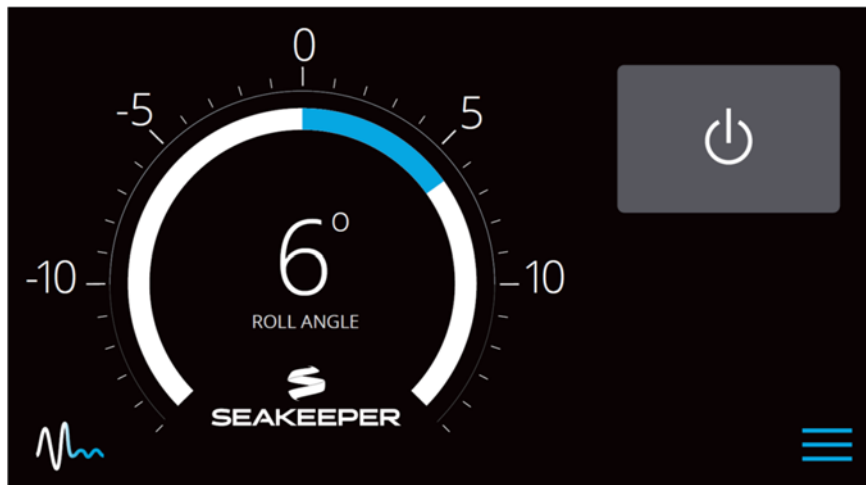
This section describes operation of the Seakeeper 6 system.

2.1 Display Screens: Overview

- 1) When 12 VDC power is applied to the Seakeeper, the display will power up and initialize. The splash screen will be displayed.



- 2) After the display has initialized, the home screen will be displayed.



- 3) The display uses a touch screen to allow users to select functions.



Section 2: SYSTEM OPERATION

Seakeeper On/Off. The button will change from grey (Seakeeper Off) to blue (Seakeeper On)



Seakeeper Stabilize On/Off. The button will change from grey (Stabilize Off) to blue (Stabilize On)



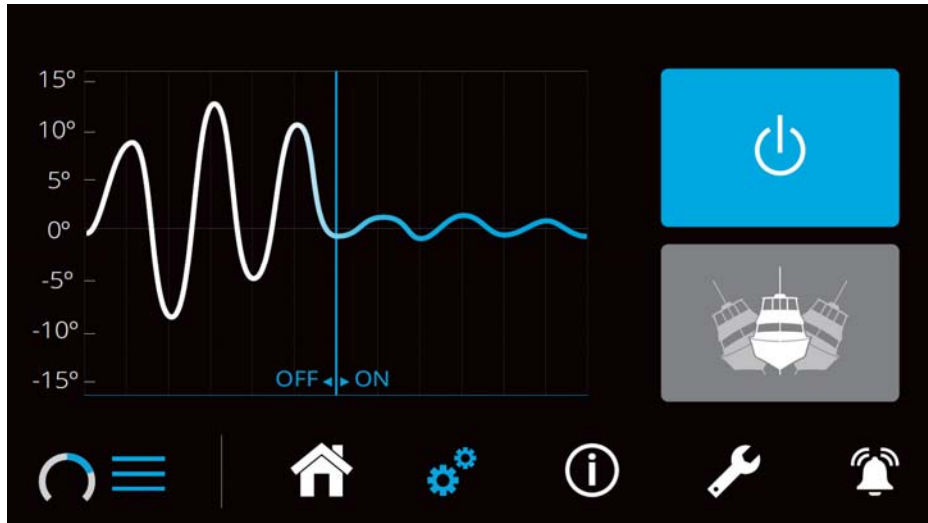
Home screen view. These buttons toggle home screen between the Roll Angle Gauge and the Roll Angle Graph as shown below.



- 4) When the menu button is pressed, the menu bar will appear or disappear at the bottom of the screen.




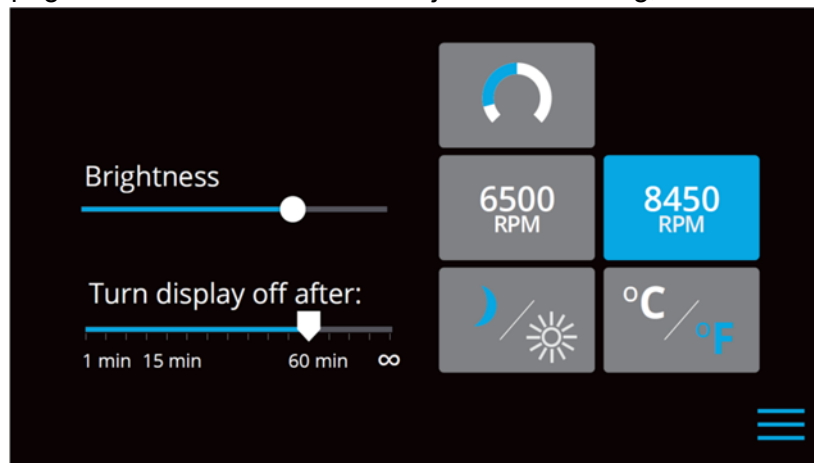
Section 2: SYSTEM OPERATION



The menu bar is used to navigate between pages. From left to right, the available pages are home, settings, information, service and alarm history. The selected page is highlighted in blue on the menu bar.



5) The settings page  allows the user adjust the following;

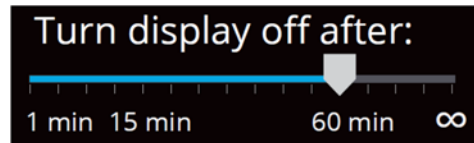


Section 2: SYSTEM OPERATION

Increase or decrease the brightness of the display with the brightness slider.



Adjust the sleep timer from 1 minutes to 60 minutes or on all of the time using sleep time slider. Touching the screen will wake the display up after it has gone to sleep.



Change the sign of the roll angle value displayed in the roll angle gauge so the gauge matches the motion of the boat. This will depend on installation orientation and will only need to be adjusted once.



Change the speed of the Seakeeper between normal operation and low power operation. The selected speed is colored blue. When power is cycled (or Seakeeper turned Off), this speed will default back to the normal operating speed. Speed selection buttons shown below are examples and may not match operating speed of installed Seakeeper.



Change the display between day and night mode. The selected mode is colored blue.



Section 2: SYSTEM OPERATION

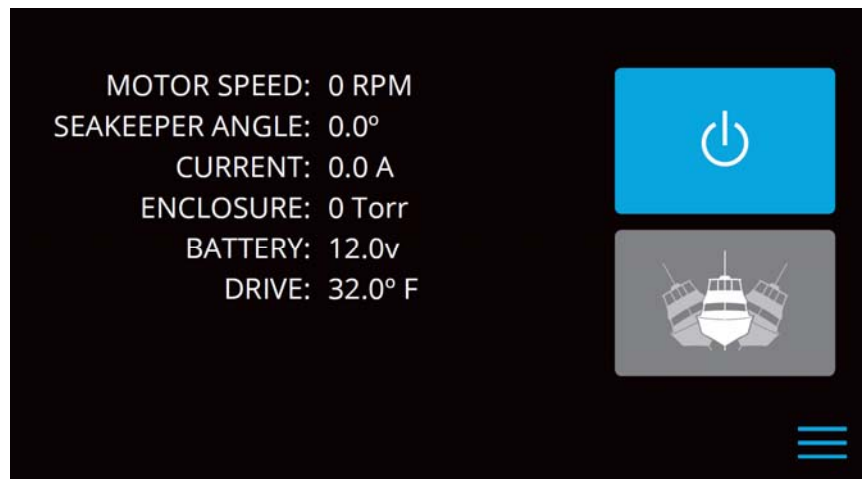
Change the units of the temperatures displayed on the service page between degrees Celsius and degrees Fahrenheit. The selected units are colored blue.



- 6) The information page displays the Seakeeper model, Seakeeper serial number, Seakeeper software versions, RUN hours, and SEA hours, and other information



- 7) The service page displays operating information from the Seakeeper.



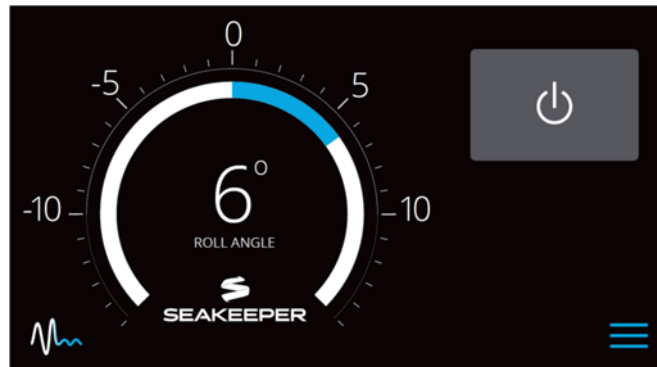
Section 2: SYSTEM OPERATION



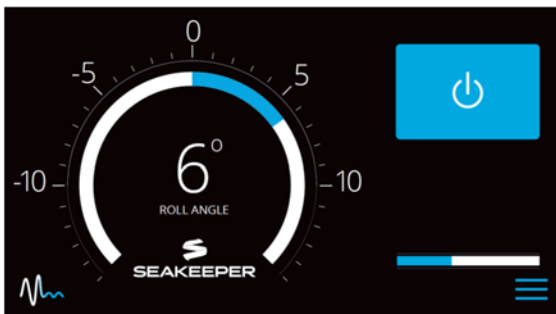
- 8) The alarm history page shows what alarms have occurred in the past and the associated run hours. The scroll bar is used to move up and down through the list.

2.2 Start-up

- 1) Make sure AC and DC power are available.
- 2) Turn on the boat's DC circuit breaker that supplies power to the Seakeeper.
- 3) Turn on the boat's AC circuit breaker that supplies power to the Motor Drive Box.
- 4) In most cases, the seawater pump will be wired to turn on when the Seakeeper or Motor Drive Box is turned on. However, in some cases the seawater pump is on a separate AC or DC circuit breaker and it is necessary to turn it on.
- 5) When the DC power is turned on the Display will initialize and the Home screen will appear.

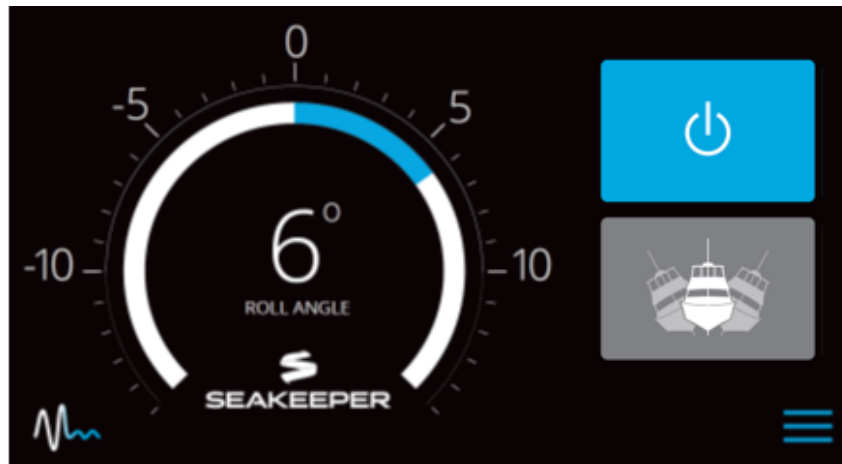


To turn the Seakeeper on, press the On/Off button, the button will turn blue. The progress bar will appear and indicate how soon the Seakeeper will be available for stabilization. When the Seakeeper is initialized and up to minimum operating speed the stabilize button will appear. At this point, the Seakeeper is available for stabilization.



Section 2: SYSTEM OPERATION

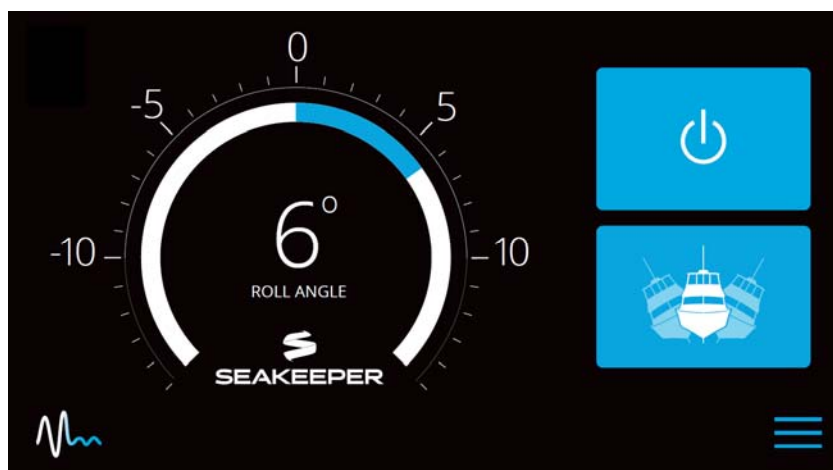
- 6) When the Seakeeper reaches its maximum operating speed where maximum stabilization is available, the progress bar will disappear and the Seakeeper is available for maximum stabilization.



2.3 Stabilization

To stabilize the boat after Seakeeper is on and above the minimum operating speed:

- 1) Press the stabilize button. The button will turn blue indicating that the Seakeeper is stabilizing the roll motion.



Section 2: SYSTEM OPERATION

If it is necessary to shutoff power to the flywheel motor and slow the flywheel for any reason, press Seakeeper On/Off button; the button will turn grey and the stabilize button will disappear indicating the command has been accepted. It takes approximately 4+ hours for the speed to drop to zero rpm.



If it is necessary to stop Seakeeper motion for any reason press the stabilize button. The stabilize button will turn grey indicating that the Seakeeper is locked. Never attempt to work on the Seakeeper until the flywheel has stopped spinning. In the event that the brake system has automatically locked the Seakeeper due to an alarm or failure, no attempt should be made to bypass the alarm or automatic lock.

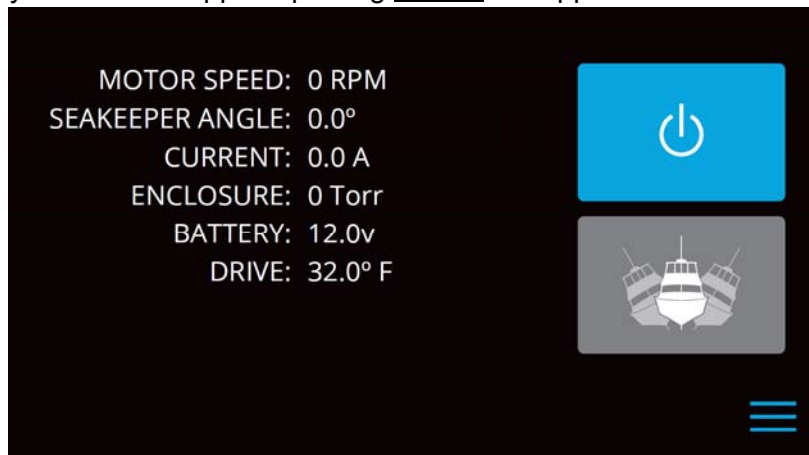
Section 2: SYSTEM OPERATION

2.4 Normal Shut-Down

The Seakeeper should be stopped when pulling into port and stabilization is no longer required. This maximizes life by allowing the Seakeeper to start the coast down cycle before cooling is shutoff. Once the vessel is secured, the AC and DC breakers can be switched OFF. The Seakeeper will continue to spool down to zero rpm. No cooling is required during this time.

- 1) Press Seakeeper On/Off button. The On/Off button will turn grey. The Seakeeper will start coasting.
- 2) Once the vessel is secured in the slip and the crew has shut down the generator and engines, switch the AC and DC breakers that control the Seakeeper OFF. The flywheel will continue to spool down to zero rpm. This can take 4+ hours from full speed.

When the flywheel has stopped spinning 0 RPM will appear on the screen



Section 2: SYSTEM OPERATION

The circuit breakers should be left on as long as possible while the Seakeeper is spinning to remove heat from the Seakeeper. During normal operation, the Seakeeper should be stopped when pulling into port and stabilization is no longer required. This maximizes long term life as it allows the Seakeeper to start the coast down cycle before cooling is shutoff. Once the vessel is secured in the slip and the crew has shut down the generator and engines, the AC and DC breakers that control the Seakeeper should be switched to the OFF position. The Seakeeper will continue to spool down to zero rpm. No cooling is required during this time. Note Seakeeper will take approximately 4+ hours to coast down to zero rpm from full speed. The Display will indicate 0 RPM when the flywheel has stopped.

Note: The seawater pump may run for up to 5 minutes after the Seakeeper is switched off and is coasting (with AC power applied).

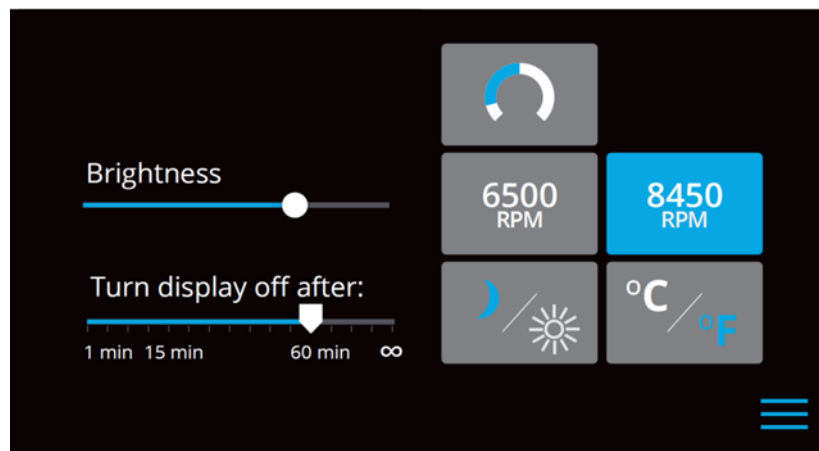
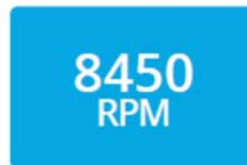
Section 2: SYSTEM OPERATION

2.5 Speed Adjustment

- 1) Press the menu button then select the settings screen.



- 2) Select the desired RPM button to adjust the Seakeeper's speed. The selected RPM button will turn blue.



Section 3: POWER FAILURES, ALARMS, AND TROUBLESHOOTING

3.0 Power Failures

There are two sources of power to the Seakeeper 6:

- 12 Volts DC powers the Seakeeper Control Box for all the control electronics.
- 110 - 230 Volts AC powers the Motor Drive Box to drive the motor inside the Seakeeper.

These are supplied on Cables 1 and 2 which are shown on Seakeeper drawing 90396, Cable Block Diagram.



The Motor Drive Box contains hazardous voltage and the cover should not be removed while the flywheel is spinning and the AC input has been disconnected for at least 10 minutes. This high voltage exists even if the flywheel is coasting down and the supply voltage has been shut off.

3.1 +12 VDC Failure

The display will be blank. Seakeeper flywheel speed will decrease. The brake is locked (no precession).

- Verify the boat's circuit breaker supplying +12 VDC has not tripped and the AC breaker is On.

When +12 VDC is restored, the display will be powered up, Splash Screen will appear, and then Home Screen will appear.

- Press Power On/Off button



The progress bar will appear and indicate flywheel speed. When the flywheel is at minimum operating speed, the stabilize button will appear so stabilization can be turned on. This may take up to 30 minutes, depending on the speed of the flywheel when the +12 VDC low current is turned back on.

Section 3: POWER FAILURES, ALARMS, AND TROUBLESHOOTING

3.2 230 VAC Failure

If the AC power is not connected, a notification screen will indicate “AC Mains Low”. If the failure is not corrected within two minutes, an “AC Mains Low” alarm will occur. The brake will lock and the Seakeeper will stop moving if stabilization was on.

- Verify the boat’s circuit breaker supplying 110-230 VAC to the Motor Drive Box has not tripped.

Once 110-230 VAC is restored:

- Press Power On/Off button



The progress bar will appear and indicate flywheel speed. When the flywheel is at minimum operating speed, the stabilize button will appear so stabilization can be turned on. This may take up to 30 minutes, depending on the speed of the flywheel when the +12 VDC low current is turned back on.

3.3 230 VAC Fluctuation, Spike or Momentary Failure

If the AC voltage to the Motor Drive Box is outside Seakeeper’s specified range (110 – 230 VAC), the Motor Drive Box will briefly shut down for protection. The Motor Drive Box will continue operation when the voltage returns to the specified range.

A brief fluctuation can happen when the generator is unable to regulate its output voltage, particularly when a large AC load is switched on or off. A momentary AC failure also happens during transition from shore power to ship’s power.

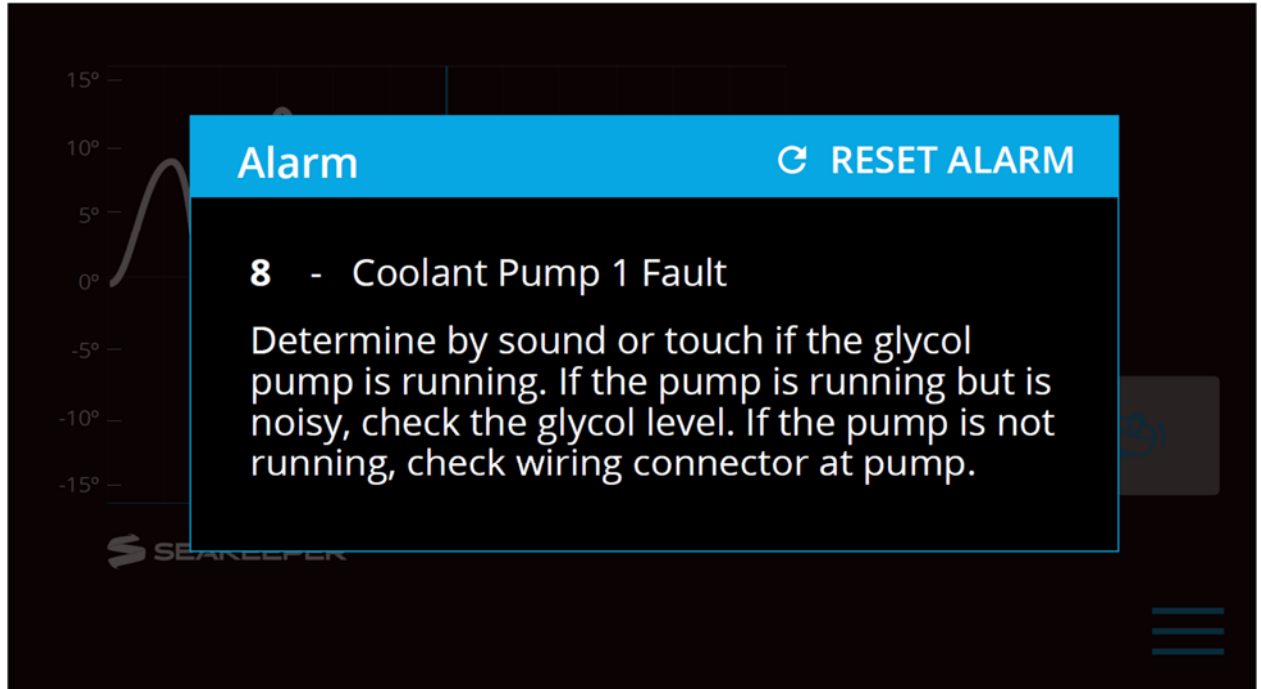
3.4 Alarms

The Seakeeper issues an alarm when it detects a malfunction that could cause damage or erratic operation. When an alarm occurs, the Seakeeper will stop and an alarm message is shown on the Display.

The alarm will not clear until the operator presses the Reset Alarm button and the alarm condition is no longer present. The operator can then press the power On/Off button again to continue Seakeeper operation.

Section 3: POWER FAILURES, ALARMS, AND TROUBLESHOOTING

- A view of a typical Alarm screen.



- To reset the Alarm, press the Reset Alarm button

Section 3: POWER FAILURES, ALARMS, AND TROUBLESHOOTING

3.5 Alarm and Warning History

The alarm history page on the Display shows the recent alarms and warnings. The alarms are in chronological order starting with the most recent. Warnings included in the history page are for issues that do not affect Seakeeper operation.

- 1) Press the menu button then select the alarm history screen.



Section 4: MAINTENANCE

4.0 MAINTENANCE

The gyro system is designed to require as little maintenance as possible. However, since the system is comprised of mechanical and electrical components that operate in a marine environment, some periodic inspections and maintenance are required. Seakeeper recommends a regular inspection interval and Scheduled Maintenance to keep the gyro running trouble-free.

If the gyro is installed in a wet space, efforts should be made to keep gyro free of salt residue from either condensation or direct exposure to salt spray. If exposed, a regular wipe down with mild soap and water with a rinse will help limit corrosion and keep the gyro assembly in good cosmetic condition. Refer to Service Bulletin 90106 for details.

The gyro comes standard with sealant and thread locker on applicable fasteners. When reinstalling all fasteners use thread locker and sealant unless otherwise specified.

4.1 REFERENCES

Service bulletins can be downloaded from the Seakeeper web-site in the technical library <https://seakeeper.com/technical-library/>

- 90026, Service Bulletin, Gyro Paint Information
- 90106, Service Bulletin, Fresh Water Rinse Notice
- 90426, Service Bulletin, Seakeeper Scheduled Maintenance Plan – Recreational Line

4.2 PRECAUTIONS



- **Scheduled maintenance must be performed by a Seakeeper certified service center to maintain warranty coverage. To locate a service center please go to <https://seakeeper.com/find-us/>**
- **Never charge the nitrogen charged accumulators with oxygen or shop air!**

Section 4: MAINTENANCE

4.3 SCHEDULED MAINTENANCE TABLE

- The following pages contain the scheduled maintenance table organized by systems: Mechanical, Hydraulic, Cooling, and Electrical. Scheduled maintenance is not covered under warranty. This table may also be found online at <https://seakeeper.com/technical-library/>

SYSTEM / COMPONENT	TASK	INTERVAL	PARTS / SPECIAL TOOLS
Mechanical / Corrosion	Inspect unit for severely corroded areas and clean and touch up with paint. See Service Bulletin 90026.	12 Months or 1000 Hours	Awlgrip Paint Part Numbers: Primer: S9001 Primer Converter: S3001 Top Coat, Snow White: F8063 Top Coat Converter: G3010
Hydraulic / Hoses	Check for cracks or chafing. If chafing found, reposition hose to provide clearance around hose. If chafing is severe, replace hose. Charge system per Service Bulletin 90025.	12 Months or 1000 Hours	Hydraulic hand pump kit
Cooling / Zinc Anode	Replace zinc anode as needed. Note the wear rate after each check and adjust inspection interval accordingly.	3 Months or 150 Hours	Replacement Zincs are available from Seakeeper.
Cooling / Hoses	Check for cracks or chafing. If damaged, replace hose. Fill cooling system and purge air.	12 Months or 1000 Hours	Anti-freeze – 50/50 Ethylene Glycol mix.
Cooling / Seawater side	Inspect heat exchanger for signs of leaks.	3 Months or 150 Hours	
Cooling / Seawater side	Fill with environmentally safe, marine anti-freeze during winter or periods of in-operation.	Winter	
Electrical / Connectors	Inspect all connectors for corrosion, replace if necessary.	12 Months or 1000 Hours	
Electrical / Grounds	Inspect all ground points for corrosion, clean as necessary, and treat with corrosion inhibitor.	12 Months or 1000 Hours	
Electrical / Gimbal Angle Sensor	Check calibration of sensor. See Service Bulletin 90083 for instructions.	Only if Angle Alarms occur	
Electrical / Cables	Check all cables and wire harness branches for cracks or chafing. Take special attention to gimbal shaft areas.	12 Months or 1000 Hours	
Electrical / Power Input	Check for seal at cable glands.	12 Months or 1000 Hours	
Electrical / Motor Power	Check integrity of motor power cable jacket.	12 Months or 1000 Hours	

Section 4: MAINTENANCE

SYSTEM / COMPONENT	TASK	INTERVAL	PARTS / SPECIAL TOOLS
Mechanical / Hydraulic Brake	Replace brake bushings, hydraulic accumulators and check valves	Inspect at 12 Months or 1000 Hours – Replace as needed or at 2000 Hours	Hydraulic hand pump kit, Brake bushing replacement tool kit, Hydraulic brake parts kit
Mechanical / Hydraulic Brake	Flush Hydraulic Oil	12 Months or 1000 Hours	Hydraulic Hand Pump Kit Oil: AW46
Cooling / System	Cooling system flush	12 Months or 1000 Hours	Fill reservoir, antifreeze – 50/50 Ethylene Glycol mix

Section 5: WARRANTY

5.0 WARRANTY, LIMITATION OF LIABILITY, PROPERTY RIGHTS

5.1 WARRANTY

The complete Seakeeper warranty details may be found on the Seakeeper website www.seakeeper.com

Seakeeper warrants that the Goods sold hereunder are free from defects in material and workmanship. This warranty is for the following period, whichever occurs first:

- a. 36 months from the date of shipment from SEAKEEPER factory
- b. 24 months from date the product put into service, which shall conclusively be presumed to be the date of sale of a vessel, on which a SEAKEEPER product is installed, to a retail customer or date put into service on an existing vessel (refit).
- c. Or, 2000 (two thousand) hours of use, subject to verification and confirmation by SEAKEEPER, INC.

This warranty does not cover normal wear of the following components or the costs associated with maintenance, repair or replacement:

- a. Surface Corrosion (Cosmetic) on any component due to exposure
- b. Heat exchanger
- c. Zinc Anodes
- d. Brake Bushings
- e. Isolation Bushings
- f. Normal preventive and scheduled maintenance and component inspections/replacements as specified in the SEAKEEPER, INC., Operation Manuals and any other Maintenance Schedule documentation.

This express warranty is in lieu of and excludes: ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, BY OPERATION OF LAW OR OTHERWISE INCLUDING WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE (WHETHER KNOWN TO SELLER OR NOT), AND ALL OTHER SUCH WARRANTIES ARE HEREBY EXPRESSLY DISCLAIMED BY SELLER AND WAIVED BY CUSTOMER/END USER. SEAKEEPER, INC. SHALL IN NO EVENT BE LIABLE TO ANY SPECIAL, DIRECT, INDIRECT, INCIDENTAL OR CONSEQUENTIAL DAMAGES FOR BREACH OF ANY WARRANTY OR OTHER OBLIGATION ARISING OUT OF THE SALE OF THE PRODUCTS, OR FROM THE USE OF THE PRODUCTS OR ANY INABILITY TO USE THE PRODUCTS.

Section 5: WARRANTY

Written notice of claimed defects shall have been given to Seakeeper within the Warranty Period, and within thirty (30) days from the date any such defect is first discovered. The Goods or parts claimed to be defective must be returned to Seakeeper, accompanied by a Return Authorization (RA) issued by Seakeeper's facility responsible for supplying Goods, with transportation prepaid by Buyer/User, with written specifications of the claimed defect.

If a warranty claim is valid, SEAKEEPER, INC. will repair or replace the Product, or part of the Product, proven to be defective, at its sole discretion, in a timeframe provided by SEAKEEPER, INC., on a reasonable best effort basis.

Under no circumstances shall Seakeeper be liable for removal of Seakeeper's Goods from Buyer's/User's equipment or re-installation into Buyer's/User's equipment. No person including any agent, distributor, or representative of Seakeeper is authorized to make any representation or warranty on behalf of Seakeeper concerning any Goods manufactured by Seakeeper.

5.2 LIMITATION OF LIABILITY

NOTWITHSTANDING ANYTHING TO THE CONTRARY, SEAKEEPER SHALL NOT BE LIABLE FOR ANY SPECIAL, INCIDENTAL, INDIRECT OR CONSEQUENTIAL DAMAGES INCLUDING BUT NOT LIMITED TO LOST PROFITS ARISING OUT OF THE PERFORMANCE, DELAYED PERFORMANCE OR BREACH OF PERFORMANCE OF THIS ORDER REGARDLESS WHETHER SUCH LIABILITY BE CLAIMED IN CONTRACT, EQUITY, TORT OR OTHERWISE. SEAKEEPER'S OBLIGATION IS LIMITED SOLELY TO REPAIRING OR REPLACING (AT ITS OPTION AND AS SET FORTH IN SECTION 5), AT ITS APPROVED REPAIR FACILITY, ANY GOODS OR PARTS WHICH PROVE TO SEAKEEPER'S SATISFACTION TO BE DEFECTIVE AS A RESULT OF DEFECTIVE MATERIALS OR WORKMANSHIP, IN ACCORDANCE WITH SEAKEEPER'S STATED WARRANTY. IN NO EVENT SHALL SEAKEEPER'S LIABILITY EXCEED THE TOTAL PURCHASE PRICE SET FORTH IN THIS ORDER.

5.3 PROPERTY RIGHTS

Except where otherwise expressly agreed, all patterns, tools, jigs and fixtures, drawings, designs, software and other materials and data developed, fabricated by Seakeeper shall be and shall remain Seakeeper's property. Except as specifically provided for in the order, Buyer shall have no right in any technical data, Intellectual Property Rights, and computer software associated with the order. Buyer shall not use or permit the use of the Goods that in any way could result in the disclosure of Seakeeper's proprietary information.

Section 6: GYRO SPECIFICATIONS

Seakeeper 6 Specifications & Summary

Rated RPM	9,700 RPM
Angular Momentum at Rated RPM	6,000 N-M-S
Anti-Rolling Torque at Rated RPM	15,690 N-M
Spool-up Time to Rated Speed	40 minutes (9,700 RPM)
Spool-up Time to Stabilization	24 minutes (7,700 RPM)
Spool-up Power	
AC Motor	2300 Watts Max
DC Control	125 Watts
Operating Power	
AC Motor (Sea state dependent)	1050-2300 Watts
DC Control	125 Watts
Voltage	
AC Input	110 VAC @ 25 Amps or 230 VAC @ 20 Amps (±10%), 50/60 Hz, Single Phase
DC Input	12 VDC @ 15 Amps
Sea Water Supply to Heat Exchanger	30 LPM (8 GPM) maximum 15 LPM (4 GPM) minimum
Ambient Air Temperature	0° - 60°C (32° - 140° F)
Weight	395 kg. (870 lbs.) bolt-in installation
Envelope Dimensions	0.765 L x 0.757 W x 0.628 H (meters) 30.1 L x 29.8 W x 24.7 H (inches)
Noise Output	At full operating RPM, steady state noise measured in the factory at a 1 meter distance measures 70-75 dBC (sound levels may be higher during spool-up).



Section 6: GYRO SPECIFICATIONS**Arrangement**

The Seakeeper 6 consists of the Flywheel, Enclosure, Foundation, Electronics, Brake, Cooling, and Cover Subsystems.

Installation Location

The Seakeeper is a torque device and does not have to be installed in a specific hull location or on the centerline. However, the Seakeeper should not be installed forward of the longitudinal center of gravity in a planing vessel.

Mounting Dimensions

See Seakeeper Drawing 90398 for bolt-in installation details.
See Seakeeper Drawing 90399 for bond-in installation details.

Loads

The installer is responsible for designing the foundation to which the Seakeeper is attached and for ensuring that this foundation can safely transfer the concentrated Seakeeper loads from the frame to the adjacent hull structure. Loads that the Seakeeper imposes on the hull structure are explained on Seakeeper Drawings 90398 and 90399; these loads do NOT include vessel motion accelerations, such as vertical slam loads which can be high for higher speed vessels.

Cooling

The Seakeeper bearings, Motor Drive Box, and hydraulic manifold are cooled by a closed water / glycol mix cooling loop that incorporates a sea water heat exchanger. The installer is responsible for providing 15 – 30 lpm (4 – 8 gpm) raw water at ambient sea temperature and 1.4 Bar (20 psi) maximum pressure to the heat exchanger.

Electrical

The installer is responsible for supplying 110 or 230 VAC, 50/60 Hz, single phase power on a 25A or 20A, respectively, service to the Motor Drive Box and 12 VDC @ 15A service to the Seakeeper Control System. Separate circuit breakers should be used for each Motor Drive Box in multiple Seakeeper installations. Similarly, separate circuit breakers should be used for each Seakeeper Control System in multiple Seakeeper installations.

Section 6: GYRO SPECIFICATIONS**Operator Controls**

A Display with integrated Keypad is used to start, operate, monitor, and shutdown the Seakeeper.

Performance

Seakeeper reduction of boat roll is a function of the boat's displacement, transverse metacentric height (GM_T) and hull damping as well as the operating conditions (speed and heading with respect to waves) and sea state. The Seakeeper controller regulates the active hydraulic brake to ensure the Seakeeper's anti-roll torque is maximized irrespective of hull characteristics or operating conditions.

Alarm and Monitoring

Sensors, alarms and shutdowns are provided to allow unattended operation. Sensors measure Seakeeper and drive temperatures, vacuum pressure, gimbal angle, brake pressure, and ship motion. The Seakeeper controller sends sensor values and alarm information to the display and also locks the brake and shuts down the motor drive in the event of an alarm condition. Seakeeper operating history during faults or alarms is recorded in the controller's memory for subsequent recall if service is needed.

Safety

The brake automatically locks the Seakeeper so it cannot generate excessive anti-rolling torque loads in the event of a system fault or alarm, loss of electrical power or loss of brake pressure. The brake can be locked from the Display or by shutting off power locally at the Motor Drive Box or Seakeeper Control System.